

# MAT290 Cheat Sheet

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## 1 Complex Numbers

$$z = a + ib$$

$$i = \sqrt{-1}$$

### 1.1 Modulus and Argument

The **modulus** or **absolute value** of  $z + iy$  is

$$|z| = \sqrt{x^2 + y^2}$$

The **argument** of a complex number must satisfy the equation

$$\tan(\theta) = \frac{y}{x} \implies \theta = \tan^{-1}\left(\frac{y}{x}\right)$$

### 1.2 Polar Form

$$z = x + iy = re^{i\theta} = r(\cos(\theta) + i \sin(\theta))$$

where  $r$  is the **modulus** of  $z$  and  $\theta$  is the **argument** of  $z$

### 1.3 Complex Conjugate

Complex Number	Complex Conjugate
$z = x + iy$	$\bar{z} = x - iy$
$z = re^{i\theta}$	$\bar{z} = re^{-i\theta}$

### 1.4 Powers of z

For  $n \in \mathbb{R}$

$$z^n = r^n(\cos(n\theta) + i \sin(n\theta))$$

For  $\alpha \in \mathbb{C}$

$$z^\alpha = e^{\alpha \ln z}$$

## 1.5 DeMoivre's Formula

$$(\cos(\theta) + i \sin(\theta))^n = \cos(n\theta) + i \sin(n\theta)$$

## 1.6 Exponential Function

$$e^z = e^{x+iy} = e^x e^{iy} = e^x (\cos(y) + i \sin(y))$$

$$|e^z| = e^x \quad \arg e^z = y + 2k\pi$$

## 1.7 Complex Logarithms

For  $z \neq 0$  and  $\theta = \arg z$

$$\ln(z) = \log_e |z| + i(\theta + 2n\pi), \quad n = 0, \pm 1, \pm 2, \dots$$

## 1.8 Principal Logarithm

$$\operatorname{Ln} z = \log_e |z| + i(\operatorname{Arg} z)$$

Where  $\operatorname{Arg}$  is the **principal argument**

## 1.9 Complex Powers

If  $z$  and  $\alpha$  are both complex powers

$$z^\alpha = e^{\alpha \ln(z)}$$

## 1.10 Trigonometric Functions

For any complex number  $z = x + iy$

$$\sin(z) = \frac{e^{iz} - e^{-iz}}{2i} \quad \cos(z) = \frac{e^{iz} + e^{-iz}}{2}$$

$$\frac{d}{dz} \sin(z) = \cos(z) \quad \frac{d}{dz} \cos(z) = -\sin(z)$$

## 1.11 Trig Identities

$$\left| \begin{array}{l} \tan(x) = \frac{\sin(x)}{\cos(x)} \\ \sec(x) = \frac{1}{\cos(x)} \end{array} \right| \left| \begin{array}{l} \csc(x) = \frac{1}{\sin(x)} \\ \cot(x) = \frac{\cos(x)}{\sin(x)} \end{array} \right|$$

$$\sin^2(x) = \frac{1 - \cos(2x)}{2}$$

$$\cos^2(x) = \frac{1 + \cos(2x)}{2}$$

$$\tan^2(x) = \frac{1 - \cos(2x)}{1 + \cos(2x)}$$

$$\begin{aligned}\sin(2x) &= 2 \sin(x) \cos(x) \\ \cos(2x) &= \cos^2(x) - \sin^2(x) \\ \cos(2x) &= 2 \cos^2(x) - 1 \\ \cos(2x) &= 1 - 2 \sin^2(x)\end{aligned}$$

$$\begin{aligned}\sin(x + y) &= \sin(x) \cos(y) + \sin(y) \cos(x) \\ \cos(x + y) &= \cos(x) \cos(y) - \sin(x) \sin(y)\end{aligned}$$

$$\sin(\alpha) \cos(\beta) = \frac{\sin(\alpha + \beta) + \sin(\alpha - \beta)}{2}$$

$$\cos(\alpha) \cos(\beta) = \frac{\cos(\alpha + \beta) + \cos(\alpha - \beta)}{2}$$

$$\sin(\alpha) \sin(\beta) = \frac{\cos(\alpha - \beta) - \cos(\alpha + \beta)}{2}$$

## 1.12 Trig Integral Identities

## 1.13 Hyperbolic Trig Functions

For any complex number  $z = x + iy$

$$\sinh(x) = \frac{e^x - e^{-x}}{2} \quad \cosh(x) = \frac{e^x + e^{-x}}{2}$$

$$\frac{d}{dz} \sinh(z) = \cosh(z) \quad \frac{d}{dz} \cosh(z) = \sinh(z)$$

## 1.14 Hyperbolic Trig Identities

$$\left| \begin{array}{l} \tanh(z) = \frac{\sinh(z)}{\cosh(z)} \\ \operatorname{sech}(z) = \frac{1}{\cosh(z)} \end{array} \right| \left| \begin{array}{l} \operatorname{csch}(z) = \frac{1}{\sinh(z)} \\ \operatorname{coth}(z) = \frac{\cosh(z)}{\sinh(z)} \end{array} \right|$$

$$\sinh(-z) = -\sinh(z)$$

$$\cosh(-z) = \cosh(z)$$

$$\cosh^2(z) - \sinh^2(z) = 1$$

$$1 - \tanh^2(z) = \operatorname{sech}^2(z)$$

$$\sinh(x + y) = \sinh(x) \cosh(y) + \cosh(x) \sinh(y)$$

$$\cosh(x + y) = \cosh(x) \cosh(y) + \sinh(x) \sinh(y)$$

$$\sin(z) = \sin(x) \cosh(y) + i \cos(x) \sinh(y)$$

$$\cos(z) = \cos(x) \cosh(y) - i \sin(x) \sinh(y)$$

## 2 Differential Equations

### 2.1 Autonomous First-Order DE's

$$\frac{dy}{dx} = f(y)$$

### 2.2 Homogenous DE's

$$\dots + a_1(x)\frac{dy}{dx} + a_0(x)y = 0$$

### 2.3 Separable Equations

$$\frac{dy}{dx} = g(x)h(y)$$

### 2.4 Linear First-Order DE's

$$a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

The solution to a linear differential equation is of the form

$$y = y_c + y_p$$

where  $y_c$  is the solution to the associated homogeneous equation and  $y_p$  is the particular solution of the non-homogeneous equation.

#### 2.4.1 Standard Form

Divide both sides of Linear DE equation by  $a_1$ :

$$\frac{dy}{dx} + P(x)y = f(x)$$

#### 2.4.2 Integrating Factor

To solve a Linear DE, first find its **standard form**

$$\frac{dy}{dx} + P(x)y = f(x)$$

and then multiply by the **integrating factor**

$$e^{\int P(x)dx}$$

to get

$$\frac{dy}{dx}e^{\int P(x)dx} + P(x)e^{\int P(x)dx}y = f(x)e^{\int P(x)dx}$$

$$\frac{dy}{dx}[e^{\int P(x)dx}y] = f(x)e^{\int P(x)dx}$$

## 2.5 Existence and Uniqueness Theorem

Suppose  $a_n(x), a_{n-1}(x), \dots, a_1(x), a_0(x)$ , and  $g(x)$  are continuous in some interval  $I$  containing  $x_0$  and  $a_n(x) \neq 0$  in  $I$ . Then the IVP has a solution in  $I$  that is unique

## 2.6 Superposition Principle for Homogeneous Equations

Let  $y_1, y_2, \dots, y_k$  be solutions of an  $n$ th order homogeneous differential equation on an interval  $I$ . Then the linear combination

$$y = c_1 y_1(x) + c_2 y_2(x) + \dots + c_k y_k(x)$$

is also a solution to the differential equation on  $I$

## 2.7 Linear Dependence/Independence

A set of functions  $f_1(x), f_2(x), \dots, f_n(x)$  is said to be linearly dependent on an interval  $I$  if there exists constants  $c_1, c_2, \dots, c_n$  not all zero, such that

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0$$

for every  $x$  in the interval. If the set of functions is not linearly dependent on the interval, it is said to be *linearly independent*

## 2.8 Wronskian

$$W(f_1, f_2, \dots, f_n) = \begin{vmatrix} f_1 & f_2 & \dots & f_n \\ f_1' & f_2' & \dots & f_n' \\ \dots & \dots & \dots & \dots \\ f_1^{(n-1)} & f_2^{(n-1)} & \dots & f_n^{(n-1)} \end{vmatrix}$$

## 2.9 Criterion for Linearly Independent Solutions

Let  $y_1, y_2, \dots, y_n$  be  $n$  solutions of the homogeneous linear  $n$ th order differential equation. The set of solutions is linearly independent on  $I$  iff  $W(y_1, y_2, \dots, y_n) \neq 0$  for every  $x$  in the interval

## 2.10 General Solution for Homogeneous Equations

$$y = y_c = c_1 y_1(x) + c_2 y_2(x) + \dots + c_k y_k(x)$$

## 2.11 General Solution for Non-homogeneous Equations

$$y = y_c + y_p = c_1 y_1(x) + c_2 y_2(x) + \dots + c_k y_k(x) + y_p$$

## 2.12 Reduction of Order

For an ODE of the form

$$y'' + P(x)y' + Q(x)y = 0$$

If  $y_1(x)$  is a known solution of the ODE on  $I$  and  $y_1(x) \neq 0$  for every  $x$  in  $I$ , then

$$y_2 = y_1(x) \int \frac{e^{-\int P(x)dx}}{y_1^2(x)} dx$$

## 2.13 Undetermined Coefficients

## 2.14 Variation of Parameters

$$y_{nh}(x) = u_1(x)y_1(x) + u_2(x)y_2(x)$$

$$W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \quad W_1 = \begin{vmatrix} 0 & y_2 \\ f(x) & y_2' \end{vmatrix} \quad W_2 = \begin{vmatrix} y_1 & 0 \\ y_1' & f(x) \end{vmatrix}$$

$$u_1' = \frac{W_1}{W} = \frac{-y_2 f(x)}{W} \quad u_2' = \frac{W_2}{W} = \frac{y_1 f(x)}{W}$$

$$u_1 = \int_0^x \frac{-y_2(t)f(t)}{W} dt \quad u_2 = \int_0^x \frac{y_1(t)f(t)}{W} dt$$

$$y_{nh}(x) = y_1(x) \int_0^x \frac{-y_2(t)f(t)}{W} dt + y_2(x) \int_0^x \frac{y_1(t)f(t)}{W} dt$$

## 2.15 Solution Types for Homogenous 2nd Degree Linear ODE's

For an ODE of the form:

$$ay'' + by' + c = 0$$

and characteristic/auxiliary polynomial:

$$ar^2 + br + c = 0$$

with roots

$$r_1 = \frac{-b - \sqrt{b^2 - 4ac}}{2a} \quad r_2 = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

### 2.15.1 Distinct Roots - Overdamped

$$y_h = c_1 e^{r_1 t} + c_2 e^{r_2 t}$$

### 2.15.2 Repeated Roots - Critically Damped

e.g.  $r_1 = r_2 = r$

$$y_h = c_1 e^{rt} + c_2 t e^{rt}$$

### 2.15.3 Complex Conjugate Roots - Underdamped

If  $r_1, r_2$  complex, then we can write  $r_1 = a + ib, r_2 = a - ib$

$$y_h = e^{ax}(c_1 \cos(bx) + c_2 \sin(bx))$$

### 3 Laplace Transform

Let  $f$  be a function defined for  $t \geq 0$

$$\mathcal{L}\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt$$

#### 3.1 Exponential Order

A function is of **exponential order** if there exists constants  $c$ ,  $M > 0$ , and  $T > 0$  s.t.  $|f(t)| \leq Me^{ct}$  for all  $t > T$

If  $f(t)$  piecewise continuous on the interval  $[0, \infty]$  and of exponential order, then  $\mathcal{L}\{f(t)\}$  exists for  $s > c$ .

#### 3.2 Basic Laplace Transforms

$$\left| \begin{array}{l} \mathcal{L}\{1\} = \frac{1}{s} \\ \mathcal{L}\{\sin(kt)\} = \frac{k}{s^2+k^2} \\ \mathcal{L}\{\sinh(kt)\} = \frac{k}{s^2-k^2} \end{array} \right| \left| \begin{array}{l} \mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}} \\ \mathcal{L}\{\cos(kt)\} = \frac{s}{s^2+k^2} \\ \mathcal{L}\{\cosh(kt)\} = \frac{s}{s^2-k^2} \end{array} \right|$$

#### 3.3 First Translation Theorem

If  $\mathcal{L}\{f(t)\} = F(s)$  and  $a$  is any real number, then

$$\mathcal{L}\{e^{at}f(t)\}(s) = \mathcal{L}\{f(t)\}(s-a) = F(s-a)$$

#### 3.4 Second Translation Theorem

The **unit step function**  $u(t-a)$  is defined as

$$u(t-a) = \begin{cases} 0 & \text{if } 0 \leq t < a \\ 1 & \text{if } t \geq a \end{cases}$$

If  $\mathcal{L}\{f(t)\} = F(s)$  and  $a > 0$ , then

$$\mathcal{L}\{f(t-a)u(t-a)\} = e^{-as}F(s)$$

#### 3.5 Transforms of Derivatives

If  $f, f', \dots, f^{(n-1)}$  are continuous on  $[0, \infty)$  and are of exponential order, and if  $f^{(n)}(t)$  is piecewise continuous on  $[0, \infty)$ , then

$$\mathcal{L}\{f^{(n)}(t)\} = s^n F(s) - s^{n-1}f(0) - s^{n-2}f'(0) - \dots - f^{(n-1)}(0)$$

where  $F(s) = \mathcal{L}\{f(t)\}$

$$\mathcal{L}\{f''(t)\} = s^2F(s) - sf(0) - f'(0)$$

$$\mathcal{L}\{f'(t)\} = sF(s) - f(0)$$

### 3.6 Derivatives of Transforms

If  $\mathcal{L}\{f(t)\} = F(s)$  and  $n = 1, 2, 3, \dots$ , then

$$\mathcal{L}\{t^n f(t)\} = (-1)^n \frac{d^n}{ds^n} F(s)$$

### 3.7 Transform of Integrals

$$\mathcal{L}\left\{\int_0^t f(\tau) d\tau\right\} = \frac{F(s)}{s}$$

$$\int_0^t f(\tau) d\tau = \mathcal{L}^{-1}\left\{\frac{F(s)}{s}\right\}$$

### 3.8 Convolution

#### 3.8.1 Convolution Operation

If  $f(t)$  and  $g(t)$  are piecewise continuous on  $[0, \infty)$ , then the **convolution** of  $f$  and  $g$ , denoted by the symbol  $f * g$ , is

$$f * g = \int_0^t f(\tau)g(t - \tau) d\tau$$

#### 3.8.2 Convolution Theorem

If  $f(t)$  and  $g(t)$  are piecewise continuous on  $[0, \infty)$  and of exponential order, then

$$\mathcal{L}\{f * g\} = \mathcal{L}\{f(t)\} \mathcal{L}\{g(t)\} = F(s)G(s)$$

#### 3.8.3 Convolution in Inverse

$$\mathcal{L}^{-1}\{F(s)G(s)\} = f * g$$

### 3.9 Dirac Delta Function

#### 3.9.1 Unit Impulse

$$\delta_a(t - t_0) = \begin{cases} 0 & \text{if } 0 \leq t < t_0 - a \\ \frac{1}{2a} & \text{if } t_0 + a \leq t \leq t_0 + a \\ 0 & \text{if } t \geq t_0 + a \end{cases}$$

#### 3.9.2 Dirac Delta Definition

$$\delta(t - t_0) = \begin{cases} \infty & \text{if } t = t_0 \\ 0 & \text{if } t \neq t_0 \end{cases}$$

Area under the distribution is 1:

$$\int_{-\infty}^{\infty} \delta(x - a) dx = 1$$



Sampling/Shifting Property:

$$\int_{-\infty}^{\infty} f(x)\delta(x-a)dx = f(a)$$

### 3.9.3 Dirac Delta Transform

For  $t_0 > 0$

$$\begin{aligned}\mathcal{L}\{\delta(t-t_0)\} &= e^{-st_0} \\ \mathcal{L}\{\delta(t)\} &= 1\end{aligned}$$

## 3.10 Additional Laplace Properties

### 3.10.1 Transform of a Periodic Function

If  $f(t)$  is

- is piecewise continuous on  $[0, \infty)$
- of exponential order
- periodic with period  $T$

$$\mathcal{L}\{f(t)\} = \frac{1}{1-e^{-sT}} \int_0^T e^{-st} f(t) dt$$

### 3.10.2 Volterra Integral Equation

$$f(t) = g(t) + \int_0^t f(\tau)h(t-\tau)d\tau$$

Taking Laplace transform of both sides:

$$F(s) = G(s) + \mathcal{L}\{f(t) * h(t)\} = G(s) + F(s)H(s)$$

### 3.10.3 Integrodifferential Equation

Circuit Analogy:

$$L \frac{di}{dt} + Ri(t) + \frac{1}{C} \int_0^t i(\tau) d\tau = E(t)$$

## 4 Inverse Laplace Transforms

### 4.1 Basic Inverse Laplace Transforms

$$\left| \begin{array}{l} \mathcal{L}^{-1}\left\{\frac{1}{s}\right\} = 1 \\ \mathcal{L}\left\{\frac{1}{s-a}\right\} = e^{at} \\ \mathcal{L}^{-1}\left\{\frac{k}{s^2+k^2}\right\} = \sin(kt) \\ \mathcal{L}^{-1}\left\{\frac{k}{s^2-k^2}\right\} = \sinh(kt) \end{array} \right| \left| \begin{array}{l} \mathcal{L}^{-1}\{1\} = \delta(t) \\ \mathcal{L}^{-1}\left\{\frac{n!}{s^{n+1}}\right\} = t^n \\ \mathcal{L}^{-1}\left\{\frac{s}{s^2+k^2}\right\} = \cos(kt) \\ \mathcal{L}^{-1}\left\{\frac{s}{s^2-k^2}\right\} = \cosh(kt) \end{array} \right|$$

### 4.2 The Inverse Laplace Transform

Suppose that  $f(t)$  is a continuous and of exponential order  $|f(t)| \leq ce^{\alpha t}$ . Then, the Inverse Laplace Transform is given by

$$f(t) = \mathcal{L}^{-1}\{F(s)\}(t) = \frac{1}{2\pi i} \int_{\sigma-i\infty}^{\sigma+i\infty} F(z)e^{zt} dt$$

Provided  $\sigma > \alpha$

### 4.3 Inverse Laplace Transform Integral

For some  $t$ , as  $x \rightarrow -\infty$  and  $|y| \rightarrow \infty$

$$f(t) = \mathcal{L}^{-1}\{F(s)\}(t) = \frac{1}{2\pi i} \int_{\sigma-i\infty}^{\sigma+i\infty} F(z)e^{zt} dt = \sum_{k=1}^n \text{Res}(e^{st}F(s), s_k)$$

For some  $t$ , as  $x \rightarrow +\infty$  and  $|y| \rightarrow \infty$

$$f(t) = \mathcal{L}^{-1}\{F(s)\}(t) = \frac{1}{2\pi i} \int_{\sigma-i\infty}^{\sigma+i\infty} F(z)e^{zt} dt = 0$$

## 5 Complex Analysis

### 5.1 Sets

#### 5.1.1 Neighborhood

A circle with radius  $p$  and center at  $z_0$  is given by

$$|z - z_0| = p$$

Note that  $|z - z_0|$  is equivalently the distance between two points.

This circular region (open disk) is called a **neighborhood**.

#### 5.1.2 Interior Point

A point  $z_0$  is called an **Interior Point** of a set  $S$  if there exists some neighborhood of  $z_0$  that lies entirely within  $S$ .

### 5.1.3 Boundary Point

A point  $z_0$  is called an **Boundary Point** of a set  $S$  if any neighborhood of  $z_0$  contains at least one point in  $S$  and one point not in  $S$ .

### 5.1.4 Open Sets

If every point  $z$  in  $S$  is an interior point, then  $S$  is an **open** set.

### 5.1.5 Closed Sets

If  $S$  contains all its boundary points, then  $S$  is a **closed** set.

### 5.1.6 Connected Set

A set is connected if any two points  $z_1, z_2$  in  $S$  can be connected by a polygonal line that lies entirely in the set.

### 5.1.7 Domain

A set  $S$  which is open and connected is called a **domain**.

## 5.2 Functions

The image  $w$  of a complex number will be some other complex number  $u + iv$

$$w = f(z) = u(x, y) + iv(x, y)$$

where  $f(z)$  is a complex function

## 5.3 Stream Flow

A complex function can also be interpreted as a **Two-Dimensional Fluid Flow**

$$f(z) = u(x, y) + iv(x, y)$$

$$\frac{dx}{dt} = u(x, y) \quad \frac{dy}{dt} = v(x, y)$$

## 5.4 Limit of a Function

Suppose the function  $f$  is defined in some neighborhood of  $z_0$ , except possibly at  $z_0$  itself. Then  $f$  is said to possess a limit at  $z_0$ , written

$$\lim_{z \rightarrow z_0} f(z) = L$$

if for each  $\epsilon > 0$ , there exists a  $\delta > 0$  such that  $|f(z) - L| < \epsilon$  whenever  $0 < |z - z_0| < \delta$

## 5.5 Continuity

A function is continuous at a point  $z_0$  if

$$\lim_{z \rightarrow z_0} f(z) = f(z_0)$$

## 5.6 Derivative

Suppose the complex function  $f$  is defined in a neighborhood of a point  $z_0$ . The derivative of  $f$  at  $z_0$  is

$$f'(z_0) = \lim_{\Delta z \rightarrow 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z}$$

Similar to real functions, **differentiability implies continuity**

## 5.7 Analyticity

A complex function  $w = f(z)$  is said to be analytic at a point  $z_0$  if  $f$  is differentiable at  $z_0$  and at every point in some neighborhood of  $z_0$

### 5.7.1 Entire Function

Functions that are analytic at any  $z$  are called **entire** functions

## 5.8 Cauchy-Riemann Equations

Suppose  $f(z) = u(x, y) + iv(x, y)$  is differentiable at a point  $z = x + iy$ . Then at  $z$  the first-order partial derivatives of  $u$  and  $v$  exist and satisfy the **Cauchy-Riemann Equations**

$$\frac{du}{dx} = \frac{dv}{dy} \quad \frac{du}{dy} = -\frac{dv}{dx}$$

## 5.9 Condition for Analyticity

Suppose the real-valued functions  $u(x, y)$  and  $v(x, y)$  are continuous and have continuous first-order partial derivatives in a domain  $D$ . If  $u$  and  $v$  satisfy the Cauchy-Riemann equations at all points of  $D$ , then the complex function  $f(z) = u(x, y) + iv(x, y)$  is analytic in  $D$ .

## 5.10 Harmonic Functions

A real-value function  $\phi(x, y)$  that has continuous second-order partial derivatives in a domain  $D$  and satisfies Laplace's equation is said to be **harmonic** in  $D$ .

$$\nabla^2 \phi(x, y) = \frac{d^2 \phi}{dx^2} + \frac{d^2 \phi}{dy^2} = 0$$

Suppose  $f(z) = u(x, y) + iv(x, y)$  is analytic in a domain  $D$ . Then the functions  $u(x, y)$  and  $v(x, y)$  are **harmonic** functions

## 6 Complex Integration

Let  $f$  be defined at points of a smooth curve  $C$  defined by  $x = x(t), y = y(t), a \leq t \leq b$ . The contour integral of  $f$  along  $C$  is

$$\int_C f(z)dz = \lim_{\|P\| \rightarrow 0} \sum_{k=1}^n f(z_k^*) \Delta z_k$$

### 6.1 Contour Integrals

If  $f$  continuous on a smooth curve  $C$  given by  $z(t) = x(t) + iy(t), a \leq t \leq b$ , then

$$\int_C f(z)dz = \int_a^b f(r(t))r'(t)dt = \int_a^b f(r)dr$$

### 6.2 Bounding Theorem

If  $f$  is continuous on a smooth curve  $C$  and if  $|f(z)| \leq M$  for all  $z$  on  $C$ ,  $|\int_C f(z)dz| \leq ML$ , where  $L$  is the length of  $C$ .

### 6.3 Circulation and Net Flux

#### 6.3.1 Book Definition

For  $f(z) = u(x, y) + i(x, y)$  and  $\vec{F} = \langle U, V \rangle$

$$\oint_C \overline{f(z)}dz = \oint_C (u - iv)(dx + idy) = \left( \oint_C f \cdot T ds \right) + i \left( \oint_C f \cdot N ds \right)$$

$$\text{circ} = \text{Re} \left( \oint_C \overline{f(z)}dz \right) = \left( \oint_C f \cdot T ds \right)$$

$$\text{flux} = \text{Im} \left( \oint_C \overline{f(z)}dz \right) = \left( \oint_C f \cdot N ds \right)$$

where  $T$  and  $N$  are the unit tangent and unit normal vectors to the positively oriented simple closed contour  $C$

#### 6.3.2 Alternative (Nachman Definition)

For  $f(z) = u(x, y) + iv(x, y)$  and a vector field with  $-V$  component  $\vec{F} = \langle U, -V \rangle = \langle P, Q \rangle$

$$\oint_C f(z)dz = [\text{circ}(\vec{F})] + i[\text{flux}(\vec{F})]$$

$$\text{circ} = \text{Re} \left( \oint_C f(z)dz \right) = \left( \oint_C f \cdot T ds \right) = \int_C P dx + Q dy$$

$$\text{flux} = \text{Im} \left( \oint_C f(z)dz \right) = \left( \oint_C f \cdot N ds \right) = \int_C P dy - Q dx$$

## 6.4 Cauchy Goursat

Suppose a function  $f$  is analytic in a simply connected domain  $D$ . Then for every simple closed contour  $C$  in  $D$

$$\oint_C f(z)dz = 0$$

Suppose  $C, C_1, \dots, C_n$  are simple closed curves with a positive orientation such that  $C, C_1, \dots, C_n$  are interior to  $C$  but the regions interior to each  $C_k, k = 1, 2, \dots, n$ , have no points in common. If  $f$  is analytic on each contour and at each point interior to  $C$  but exterior to all the  $C_k, k = 1, 2, \dots, n$ , then

$$\oint_C f(z)dz = \sum_{k=1}^n \oint_{C_k} f(z)dz$$

Additionally, for any  $z_0 \in \mathbb{C}$  interior to any simple closed contour  $C$ , then

$$\oint_C \frac{1}{(z - z_0)^n} dz = \begin{cases} 2\pi i & \text{if } n = 1 \\ 0 & \text{if } n \in \mathbb{Z}, n \neq 1 \end{cases}$$

## 6.5 Independence of Path and Implications of Analyticity

Let  $z_0$  and  $z_1$  be points in domain  $D$ . A contour integral  $\int_C f(z)dz$  is **independent of the path** if the value of the integral is the same for any contour  $C$  in  $D$  with initial and end points  $z_0$  and  $z_1$ .

If  $f$  is an *analytic* in a simply connected domain  $D$ , then  $\int_C f(z)dz$  is independent of the path  $C$ .

## 6.6 Existence of an Antiderivative

If  $f$  is analytic in a simply connected domain  $D$ , then  $f$  has an anti-derivative in  $D$ ; that is, there exists a function  $F$  s.t.  $F'(z) = f(z)$  for all  $z$  in  $D$

## 6.7 Fundamental Theorem for Contour Integrals

Suppose  $f$  is continuous in a domain  $D$  and  $F$  is an antiderivative of  $f$  in  $D$ . Then for any contour  $C$  in  $D$  with initial point  $z_0$  and terminal point  $z_1$ ,

$$\int_C f(z)dz = F(z_1) - F(z_0)$$

## 6.8 Cauchy Integral Formula's

Let  $f$  be analytic in a simply connected domain  $D$ , and let  $C$  be a simple closed contour lying entirely within  $D$ . If  $z_0$  is any point within  $C$ , then

$$f(z_0) = \frac{1}{2\pi i} \int_C \frac{f(z)}{(z - z_0)} dz$$
$$f^n(z_0) = \frac{n!}{2\pi i} \oint_C \frac{f(z)}{(z - z_0)^{n+1}} dz$$

## 6.9 Liouville's Theorem

The only bounded entire functions are constants.

## 6.10 Cauchy's Inequality

$$|f^{(n)}(z_0)| \leq \frac{n!M}{r^n}$$

where  $M$  is a real number such that  $|f(z)| \leq M$  for all points  $z$  on  $C$ , and  $C$  is the contour  $|z - z_0| = r$ .

# 7 Sequences and Series

$$\sum_{k=0}^{\infty} az^k = \lim_{k \rightarrow \infty} a + az + az^2 + az^3 + \dots + az^k = \frac{a}{1-z}$$

## 7.1 Convergence/Divergence Tests

### 7.1.1 nth Term Test

If  $\lim_{n \rightarrow \infty} z_n \neq 0$ , then the series  $\lim_{k=1}^{\infty} z_k$  diverges.

### 7.1.2 Ratio Test

$$\lim_{n \rightarrow \infty} \left| \frac{z_{n+1}}{z_n} \right| = L$$

- If  $L < 1$ , series *converges absolutely*
- If  $L > 1$  or  $L = \infty$ , the series *diverges*
- If  $L = 1$ , the test is inconclusive

### 7.1.3 Root Test

$$\lim_{n \rightarrow \infty} \sqrt[n]{|z_n|} = L$$

- If  $L < 1$ , series *converges absolutely*
- If  $L > 1$  or  $L = \infty$ , the series *diverges*
- If  $L = 1$ , the test is inconclusive

## 7.2 Geometric Series

If  $|z| < 1$ , then

$$\sum_{k=0}^{\infty} az^k = \frac{a}{1-z}$$

### 7.3 Power Series

$$\sum_{k=0}^{\infty} a_k (z - z_0)^k$$

Represents an analytic function within its circle of convergence.

### 7.4 Taylor's Theorem

Let  $f$  be analytic within a domain  $D$  and let  $z_0$  be a point in  $D$ . Then

$$f(z) = \sum_{k=0}^{\infty} \frac{f^{(k)}(z_0)}{k!} (z - z_0)^k$$

### 7.5 Maclaurin Series

Taylor series centered at  $z_0 = 0$

$$f(z) = \sum_{k=0}^{\infty} \frac{f^{(k)}(0)}{k!} (z)^k$$

### 7.6 Laurent's Theorem

Let  $f$  be analytic within the annular domain  $D$  defined by  $r < |z - z_0| < R$ . Then,  $f$  has the series representation

$$f(z) = \sum_{k=-\infty}^{\infty} a_k (z - z_0)^k$$

valid for  $r < |z - z_0| < R$ . The coefficients  $a_k$  are given by

$$a_k = \frac{1}{2\pi i} \oint_C \frac{f(s)}{(s - z_0)^{k+1}} ds$$

where  $k = 0, \pm 1, \pm 2, \dots$ , and  $C$  is a simply closed curve that lies entirely within  $D$  and has  $z_0$  in its interior.

Note: Assuming  $f(z)$  analytic on domain  $D$ ,

$$a_k = \frac{1}{2\pi i} \oint_C \frac{f(s)}{(s - z_0)^{k+1}} ds = \frac{1}{(k)!} \frac{d^k}{dz^k} f(z) \Big|_{z=z_0}$$

### 7.7 Common Taylor Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \frac{x^5}{5!} + \dots + \frac{x^n}{(n)!} = \sum_{k=0}^{\infty} \frac{x^k}{k!}$$

$$\cos(x) = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots = \sum_{k=0}^{\infty} \frac{(-1)^k}{(2k)!} x^{2k}$$

$$\sin(x) = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots = \sum_{k=0}^{\infty} \frac{(-1)^k}{(2k+1)!} x^{2k+1}$$



## 8 Poles, Zeros, Residues

### 8.1 Zeros

$z_0$  is a *zero* of a function  $f$  if  $f(z_0) = 0$ . An analytic function  $f$  has a zero of order  $n$  at  $z = z_0$  if

$$f(z_0) = 0, f'(z_0) = 0, \dots, f^{n-1}(z_0) = 0, \text{ but } f^n(z_0) \neq 0$$

### 8.2 Singularities

Type of Singularities	Order	Laurent Series
Removable Singularity	$n = 0$	$a_0 + a_1(z - z_0) + a_2(z - z_0)^2 + \dots$
Pole of Nth Order	$n = n$	$\frac{a_{-n}}{(z - z_0)^n} + \frac{a_{-(n-1)}}{(z - z_0)^{n-1}} + \dots + \frac{a_{-1}}{(z - z_0)} + a_0 + a_1(z - z_0) + \dots$
Simple Pole	$n = 1$	$\frac{a_{-1}}{(z - z_0)} + a_0 + a_1(z - z_0) + \dots$
Essential Singularity	$n = \infty$	$\dots + \frac{a_{-2}}{(z - z_0)^2} + \frac{a_{-1}}{(z - z_0)} + a_0 + a_1(z - z_0) + \dots$

### 8.3 Poles

If  $f$  and  $g$  are analytic at  $z = z_0$  and  $f$  has a zero of order  $n$  at  $z = z_0$  and  $g(z_0) \neq 0$ , then the function  $F(z) = \frac{g(z)}{f(z)}$  has a pole of order  $n$  at  $z = z_0$ .

### 8.4 Residue

$$\text{Res}(f(z), z_0) = a_{-1} = \frac{1}{2\pi i} \oint_C f(z) dz$$

Rearranging gives

$$2\pi i a_{-1} = 2\pi i \text{Res}(f(z), z_0) = \oint_C f(z) dz$$

### 8.5 Calculating Residue

#### 8.5.1 Simple Pole

$$\text{Res}(f(z), z_0) = \lim_{z \rightarrow z_0} (z - z_0) f(z)$$

#### 8.5.2 Pole of Order N

$$\text{Res}(f(z), z_0) = \frac{1}{(n-1)!} \lim_{z \rightarrow z_0} \frac{d^{n-1}}{dz^{n-1}} (z - z_0)^n f(z)$$

#### 8.5.3 Non-Rational Functions

$$\text{Res}(f(z), z_0) = \frac{g(z_0)}{h'(z_0)}$$

## 8.6 Cauchy Residue Theorem

Let  $D$  be a simply connected domain and  $C$  be a simply closed curve inside  $D$ . Suppose  $f(z)$  analytic on  $C$  and at region enclosed by  $C$  except at finitely many isolated singular points  $z_1, z_2, \dots, z_n$ . Then

$$\oint_C f(z)dz = 2\pi i \sum_{j=1}^N \text{Res}(f(z), z_j)$$

## 9 Real Value Integrals

### 9.1 Trig Function Integrals

For integrals of the form:

$$\int_0^{2\pi} F(\cos(\theta) \sin(\theta))d\theta$$

Apply change of variables using  $z = e^{i\theta} = \cos(\theta) + i \sin(\theta)$ :

$$\oint_C F\left(\frac{1}{2}(z + z^{-1}), \frac{1}{2i}(z - z^{-1})\right) \frac{dz}{iz}$$

Where  $C$  is  $|z| = 1$  and  $d\theta = \frac{dz}{iz}$

$$\cos(\theta) = \frac{e^{i\theta} + e^{-i\theta}}{2} = \frac{1}{2}(z + z^{-1})$$

$$\sin(\theta) = \frac{e^{i\theta} - e^{-i\theta}}{2i} = \frac{1}{2i}(z - z^{-1})$$

### 9.2 Cauchy Principal Value

For integrals of the form:

$$\int_{-\infty}^{\infty} f(x)dx = \lim_{r \rightarrow \infty} \int_{-r}^0 f(x)dx + \lim_{r \rightarrow \infty} \int_0^r f(x)dx$$

If both limits exist, the integral is *convergent*. Otherwise, integral is *divergent*.

$$\text{P.V.} \int_{-\infty}^{\infty} f(x)dx = \lim_{r \rightarrow \infty} \int_{-r}^r f(x)dx$$

If the integral is *convergent*, then its P.V. (Principal Value) is equal to the value of the integral

#### 9.2.1 Jordan Lemma

Suppose  $f(z) = \frac{P(z)}{Q(z)}$ , where the degree of  $P(z)$  is  $n$  and the degree of  $Q(z)$  is  $m$ .  $C_r$  is a semicircular contour  $z = Re^{i\theta}$ ,  $0 \leq \theta \leq \pi$ , then

If  $m > n + 1$ , then

$$\int_{C_r} f(z)dz = \int_{C_r} \frac{P(z)}{Q(z)}dz \rightarrow 0 \quad \text{as } R \rightarrow \infty$$

If  $m > n$  and  $\alpha > 0$ , then

$$\int_{C_r} f(z)e^{i\alpha z} dz = \int_{C_r} \frac{P(z)}{Q(z)} e^{i\alpha z} dz \rightarrow 0 \quad \text{as } R \rightarrow \infty$$

### 9.3 Indented Contours

Suppose  $f$  has a simple pole  $z = c$  on the real axis. If  $C_\epsilon$  is the contour defined by  $z = c + re^{i\theta}$  for  $0 \leq \theta \leq \pi$ , then

$$\lim_{\epsilon \rightarrow 0} \int_{C_\epsilon} f(z) dz = \pi i \text{Res}(f(z), c)$$

If  $\tilde{C}$  is the indented contour,

$$\oint_{\tilde{C}} f(z) dz = P.V. \int_{-\infty}^{\infty} f(x) dx + \lim_{\epsilon \rightarrow 0} \int_{C_\epsilon} f(z) dz$$

$$P.V. \int_{-\infty}^{\infty} f(x) dx = \sum_{j=1}^N \text{Res}(f(z), z_j) - \pi i \text{Res}(f(z), c)$$

## 10 Absolute Value and Inequality

### 10.1

#### 10.2 Triangle Inequality

$$||x| - |y|| \leq |x + y| \leq |x| + |y|$$